



A cross-based alternating least squares method for CP tensor decomposition

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Based on a joint work with
Peter Benner (MPI Magdeburg)



Organization

1. CP tensor decomposition and ALS
2. Deterministic cross-based sampling
3. Numerical experiments
4. Conclusion



CP tensor decomposition

- Tensors: $\mathcal{X} \in \mathbb{R}^{n_1 \times \dots \times n_d}$ describe multiway data in chemometrics, neuroscience, parametric PDEs, recommender systems, ...
- CP tensor decomposition with factor matrices:

$$\mathcal{X} \approx \tilde{\mathcal{X}} = \underbrace{\sum_{j=1}^r \mathbf{a}_j^{(1)} \otimes \dots \otimes \mathbf{a}_j^{(d)}}_{=:\llbracket A_1, \dots, A_d \rrbracket} \in \mathbb{R}^{n_1 \times \dots \times n_d}, \quad A_k = [\mathbf{a}_1^{(k)}, \dots, \mathbf{a}_r^{(k)}] \in \mathbb{R}^{n_k \times r}.$$

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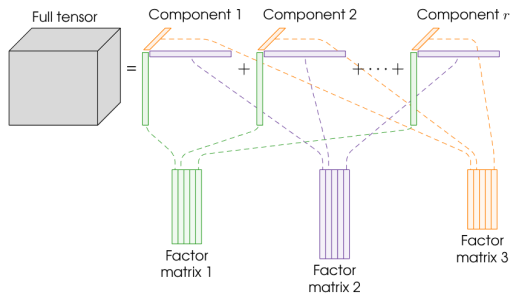


Figure: Taken from Kolda and Bader. Tensor Decompositions for Data Science, Cambridge University Press, 2025.

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- Objective: find factors with moderate rank $r \ll n_k$:

$$A_1, \dots, A_d = \arg \min_{A_1, \dots, A_d} \|\mathcal{X} - \llbracket A_1, \dots, A_d \rrbracket\|_F^2.$$

- Once fitted: data compression $O(dnr)$, interpretation of factors, cheap downstream computations, ...



Alternating least squares (ALS) method

- Objective: find factors with moderate rank $r \ll n_k$:

$$A_1, \dots, A_d = \arg \min_{A_1, \dots, A_d} \|\mathcal{X} - \llbracket A_1, \dots, A_d \rrbracket\|_{\text{F}}^2.$$

- ALS: update one factor at a time while fixing others.

- 1: Initialize factor matrices A_k (e.g., randomly).

- 2: **for** $k = 1, 2, \dots, d$ **do**

- 3: $A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|\mathcal{X} - \llbracket A_1, \dots, A_{k-1}, Y, A_{k+1}, \dots, A_d \rrbracket\|_{\text{F}}^2$

- 4: **end for**

- In matrix form, ALS update solves

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|\mathcal{X}_{(k)} - Y Z_k^\top\|_{\text{F}}^2.$$

- $\mathcal{X}_{(k)} \in \mathbb{R}^{n_k \times N_k}$: mode- k unfolding of $\mathcal{X}$.

- $Z_k = A_d \odot \dots \odot A_{k+1} \odot A_{k-1} \odot \dots \odot A_1 \in \mathbb{R}^{N_k \times r}$, $N_k = \prod_{j \neq k} n_j$.

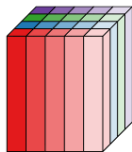


Alternating least squares (ALS) method

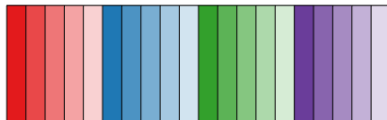
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(a) Mode-1 fibers.



(b) Mode-1 unfolding.

Figure: Taken from Kolda and Bader. Tensor Decompositions for Data Science, Cambridge University Press, 2025.



Alternating least squares (ALS) method

- In matrix form, ALS update solves

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|\mathcal{X}_{(k)} - Y Z_k^\top\|_F^2.$$

- $\mathcal{X}_{(k)} \in \mathbb{R}^{n_k \times N_k}$: mode- k unfolding of $\mathcal{X}$.
- $Z_k = A_d \odot \cdots \odot A_{k+1} \odot A_{k-1} \odot \cdots \odot A_1 \in \mathbb{R}^{N_k \times r}$, $N_k = \prod_{j \neq k} n_j$.
- $\odot$ denotes the Khatri–Rao (columnwise Kronecker) product:

$$A \odot B = [\mathbf{a}_1 \otimes \mathbf{b}_1, \mathbf{a}_2 \otimes \mathbf{b}_2, \dots, \mathbf{a}_r \otimes \mathbf{b}_r] \in \mathbb{R}^{(mp) \times r} \quad \text{for } A \in \mathbb{R}^{m \times r}, B \in \mathbb{R}^{p \times r}.$$

- Rewriting the LS problem:

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k Y^\top - \mathcal{X}_{(k)}^\top\|_F^2.$$

- Very tall and skinny $Z_k \in \mathbb{R}^{N_k \times r}$ with $N_k \gg r$.



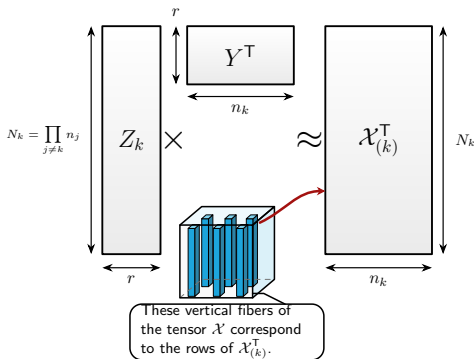
Classical CP-ALS: curse of dimensionality

- In matrix form, CP-ALS update solves:

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k Y^\top - \mathcal{X}_{(k)}^\top\|_F^2.$$

- Very tall and skinny Z_k with $N_k \gg n_k > r$. Each solve costs $O(n^d)$.
- Result: classical ALS becomes infeasible for moderate d unless we can shrink each LS.

CP ALS Iteration (Full LS)



Solve:

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k Y^\top - \mathcal{X}_{(k)}^\top\|_F^2$$



Randomized sampling

- Idea: sample s rows ($s \ll N_k$) to form

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k Y^\top - \mathcal{X}_{(k)}^\top\|_F^2.$$



Randomized sampling

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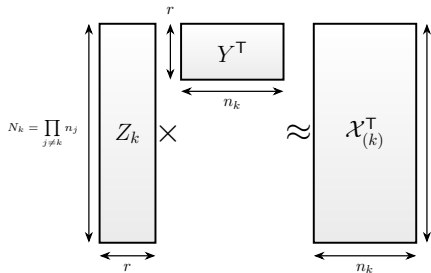
$$\mathbf{A}_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k(\mathcal{I}, :) Y^\top - \mathcal{X}_{(k)}^\top(\mathcal{I}, :)\|_F^2.$$

- Here $Z_k(\mathcal{I}, :)$ denotes rows indexed by $\mathcal{I} \subseteq \{1, \dots, N_k\}$, $\#\mathcal{I} = s$.



Randomized sampling

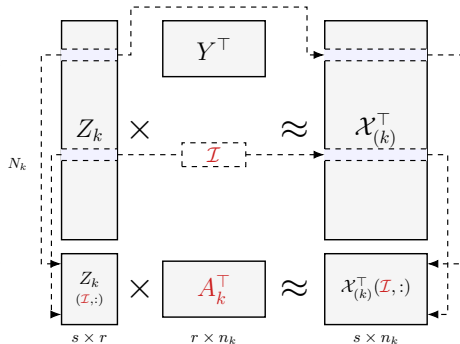
CP ALS Iteration (Full LS)



Solve:

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k Y^\top - \mathcal{X}_{(k)}^\top\|_F^2$$

Sampled CP ALS Iteration (Reduced LS)



Solve:

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k(\mathcal{I}, :) Y^\top - \mathcal{X}_{(k)}^\top(\mathcal{I}, :)\|_F^2$$



Randomized sampling

- Idea: sample s rows ($s \ll N_k$) to form

$$\mathbf{A}_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k(\mathcal{I}, :)Y^\top - \mathcal{X}_{(k)}^\top(\mathcal{I}, :)\|_F^2.$$

- Here $Z_k(\mathcal{I}, :)$ denotes rows indexed by $\mathcal{I} \subseteq \{1, \dots, N_k\}$, $\#\mathcal{I} = s$.
- Randomized choices (uniform¹, leverage-score²) reduce cost but:
 - Need $s \gg r$.
 - Variance: unlucky draws miss informative fibers.
- Can we deterministically select exactly $s = r$ informative rows instead?

¹Battaglino, Ballard, Kolda. A practical randomized CP tensor decomposition, SIMAX. 2018

²Larsen, Kolda. Practical leverage-based sampling for low-rank tensor decomposition, SIMAX. 2022



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Selecting exactly r informative rows

- Recall ALS update:

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k Y^\top - \mathcal{X}_{(k)}^\top\|_F^2.$$

- Goal: choose $\mathcal{I} \subseteq \{1, \dots, N_k\}$ “wisely” with $\#\mathcal{I} = r$ to solve instead

$$A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|Z_k(\mathcal{I}, :) Y^\top - \mathcal{X}_{(k)}(\mathcal{I}, :)^{\top}\|_F^2.$$

Lemma (Following Lemma 4.1 of [Sorensen/Embree'16, A DEIM induced CUR factorization.])

The sampled LS solution A_k is not too worse than the full LS solution A_k :

$$\|Z_k A_k^\top - \mathcal{X}_{(k)}^\top\|_F \leq \|Z_k Z_k(\mathcal{I}, :)^{-1}\|_2 \|Z_k A_k^\top - \mathcal{X}_{(k)}^\top\|_F.$$

- The quality of A_k relies on $\|Z_k Z_k(\mathcal{I}, :)^{-1}\|_2$. How to select $\mathcal{I}$ to control this norm?



maxvol provides the needed control

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The sampled LS solution A_k is not too worse than the full LS solution A_k :

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- Goal: select $\mathcal{I}$ to control the spectral norm $\|Z_k Z_k(\mathcal{I}, :)^{-1}\|_2$.
- maxvol³ greedily finds a submatrix with (approx.) maximal volume.

Lemma (Following Lemma 2.1 of [Goreinov/Tyrtshnikov/Zamarashkin'97])

If $\mathcal{I} = \text{maxvol}_\mu(A)$ for $A \in \mathbb{R}^{m \times r}$, then $\|AA(\mathcal{I}, :)^{-1}\|_2 \leq \sqrt{1 + \mu^2(m-r)r}$ (tight bound).

- μ : slightly larger than 1 as a tolerance (e.g. $\mu = 1.01$). Cost per call: $O(mr^2)$.
- Perfect for our goal—if only we could run it on $Z_k \in \mathbb{R}^{N_k \times r}$, $N_k = \prod_{j \neq k} n_j$!

³Goreinov, Oseledets, Savostyanov, Tyrtshnikov, Zamarashkin. How to find a good submatrix. 2010



Why we cannot apply maxvol directly

- Recall

$$Z_k = A_d \odot \cdots \odot A_{k+1} \odot A_{k-1} \odot \cdots \odot A_1 \in \mathbb{R}^{N_k \times r}, \quad N_k = \prod_{j \neq k} n_j.$$

- Z_k has $N_k = \prod_{j \neq k} n_j$ rows: even storing one column is prohibitive.
- A single $\text{maxvol}(Z_k)$ call would cost $O(N_k r^2)$ and require explicit Khatri–Rao evaluation.
- Need a structured workaround that never forms Z_k but inherits (close to) maxvol guarantees.
- Solution: leverage the Khatri–Rao structure of Z_k to build a hierarchical sampling scheme.



Hierarchical selection via Khatri–Rao tree

■ Recall

$$Z_k = \underbrace{A_d \odot \cdots \odot A_{k+1}}_{=Z_{\geq k+1}} \odot \underbrace{A_{k-1} \odot \cdots \odot A_1}_{=Z_{\leq k-1}} \in \mathbb{R}^{N_k \times r}, \quad N_k = \prod_{j \neq k} n_j.$$

■ With base cases $Z_{\geq d} = A_d$, $Z_{\leq 1} = A_1$, recursively build:

$$Z_{\geq k+1} = Z_{\geq k+2} \odot A_{k+1}, \quad Z_{\leq k-1} = A_{k-1} \odot Z_{\leq k-2},$$

■ Let $\hat{Z}_{\geq d} = \text{maxvol}(A_d) \in \mathbb{R}^{r \times r}$, $\hat{Z}_{\leq 1} = \text{maxvol}(A_1) \in \mathbb{R}^{r \times r}$. Recursively compute:

$$\hat{Z}_{\geq k+1} = \text{maxvol}(\hat{Z}_{\geq k+2} \odot A_{k+1}) \in \mathbb{R}^{r \times r}, \quad \hat{Z}_{\leq k-1} = \text{maxvol}(A_{k-1} \odot \hat{Z}_{\leq k-2}) \in \mathbb{R}^{r \times r}.$$

■ Final merging: $\hat{Z}_k = \text{maxvol}(\hat{Z}_{\geq k+1} \odot \hat{Z}_{\leq k-1})$.

■ Note: $\hat{Z}_{\geq k+1}$, $\hat{Z}_{\leq k-1}$ can be stored and reused across ALS iterations.



The CP-ACLS algorithm

Algorithm 1 CP-ACLS with hierarchical maxvol sampling

```

1: for  $k = d, \dots, 2$  do                                     ▷ Initialize upper chain  $O(dnr^3)$ 
2:    $\hat{Z}_{\geq k} = \text{maxvol}(\hat{Z}_{\geq k+1} \odot A_k)$ 
3: end for
4: repeat
5:   for  $k = 1, \dots, d$  do                                     ▷ forward sweep
6:      $\hat{Z}_k = \text{maxvol}(\hat{Z}_{\geq k+1} \odot \hat{Z}_{\leq k-1})$  (for  $k \neq 1, d$ )      ▷  $O(r^4)$ 
7:     Compute physical indices  $\mathcal{I}$  s.t.  $\hat{Z}_k = Z_k(\mathcal{I}, :)$ .
8:     Solve sampled LS:  $A_k = \arg \min_{Y \in \mathbb{R}^{n_k \times r}} \|\hat{Z}_k Y^\top - \mathcal{X}_{(k)}(\mathcal{I}, :)^{\top}\|_{\text{F}}^2$ .    ▷  $O(nr^2 + r^3)$ 
9:      $\hat{Z}_{\leq k} = \text{maxvol}(A_k \odot \hat{Z}_{\leq k-1})$  (for  $k \neq d$ )      ▷ update lower chain  $O(nr^3)$ 
10:  end for
11:  Do backward sweep  $k = d - 1, \dots, 1$  similarly    ▷ reuse lower chain, update upper chain
12: until maximum epochs or tolerance satisfied

```



Error guarantees of hierarchical maxvol

Theorem

Assume every *maxvol* call is performed with tolerance $\mu \geq 1$. Then the selected rows $\hat{Z}_k$ of Z_k satisfy

$$\|Z_k \hat{Z}_k^{-1}\|_2 \leq \sqrt{1 + \mu^{2d} r^{2(d-1)} (n^{d-1} - r)r},$$

therefore

$$\|Z_k A_k^\top - \mathcal{X}_{(k)}^\top\|_F \leq \sqrt{1 + \mu^{2d} r^{2(d-1)} (n^{d-1} - r)r} \|Z_k A_k^\top - \mathcal{X}_{(k)}^\top\|_F.$$

- Bound is very pessimistic, but in practice growth is much milder.
- Even directly applying DEIM (or LUPP, QRCP) on full Z_k yields similar bounds:

$$\|Z_k \hat{Z}_k^{-1}\|_2 \leq \sqrt{n^{d-1} r} 2^{r-1}$$

- Cost: $O(dnr^3)$ per sweep.



Cross vs. random sampling for CP-ALS

	CP-ACLS	CP-ARLS (lev) ⁴	CP-ARLS (uni) ⁵
LS accuracy $\ \hat{R}\ /\ R\ \leq$	$1 + \mu^d r^d n^{d/2}$	$1 + \varepsilon$ (w.p. $1 - \delta$)	None
# samples	r	$r^d \max\{1700 \cdot \log(r/\delta), 1/(\delta\varepsilon)\}$	None
Complexity per sweep	$O(dnr^3)$	$O(dsnr)$	$O(dsnr)$

- CP-ACLS needs only r samples, but with a **pessimistic** accuracy guarantee.
- CP-ARLS (lev) guarantees accuracy with high $\mathbb{P}$, but needs **pessimistic** # samples.
- CP-ACLS may be more efficient when $s > r^2$.
- Not clear a priori which method is better from theory alone.
- Cross-based methods are very successful in the world of tensor trains, so promising to try here too!

⁴Larsen, Kolda. Practical leverage-based sampling for low-rank tensor decomposition, SIMAX. 2022

⁵Battaglino, Ballard, Kolda. A practical randomized CP tensor decomposition, SIMAX. 2018



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Numerical experiments: setting

- Use MATLAB TensorToolbox⁶ implementation of CP-ALS, ARLS (lev), ARLS (uni).
- Implemented CP-ACLS as a new solver in the toolbox.
- Default sample sizes for CP-ARLS (lev) is $s = 2^{17}$, CP-ARLS (uni) is $s = 10r \log(r)$.
- But we choose $s = r^2$ for them to make fairer comparisons.
- Measure of fit (close to 1 is better):

$$\text{Fit} = 1 - \frac{\|\mathcal{X} - \tilde{\mathcal{X}}\|_F}{\|\mathcal{X}\|_F} \in [0, 1].$$

⁶Bader, Kolda. MATLAB Tensor Toolbox Version 3.7, 2025.



Experiment 1: synthetic tensor

- Following examples in TensorToolbox documentation.
- Generate rank-5 CP tensor of size $100 \times 100 \times 100 \times 100$ with collinearity 0.9 and Gaussian noise (0.01 relative noise).
- Rank-5 CP fits initialized with the same random orthogonal factors.

Method	Time (s)	Fit
CP-ACLS	0.0396	0.9138
CP-ARLS (lev)	0.1978	0.9733
CP-ARLS (uni)	0.0341	0.8798
CP-ALS	19.380	0.9863



Experiment 2: turbulent flow tensor

- An example tensor from TensorToolbox documentation.
- Dataset: Miranda turbulent flow tensor ($2048 \times 256 \times 256$) from SDRBench⁷.
- Rank-10 CP fits initialized with the same random orthogonal factors.

Method	Time (s)	Fit
CP-ACLS	0.1742	0.8623
CP-ARLS (lev)	0.4098	0.9165
CP-ARLS (uni)	0.1159	0.9048
CP-ALS	10.352	0.9287

⁷K. Zhao et al., SDRBench: Scientific Data Reduction Benchmark for Lossy Compressors, IEEE Big Data 2020.



Experiment 3: discretization of a function

- An example from Chebfun3F paper⁸.
- Consider

$$f(x_1, \dots, x_d) = \frac{1}{10^{-5} + \sum_{k=1}^d x_k^2}, \quad x_k \in [-1, 1].$$

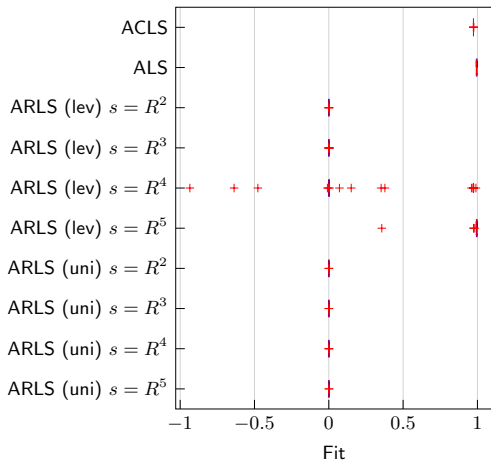
- Discretize f with $d = 5$ and $n = 30$ points in each dimension on Chebyshev grid.
- Rank-5 CP fits for resulting tensor of size $30 \times 30 \times 30 \times 30 \times 30$.
- Vary sample sizes for CP-ARLS (lev) and CP-ARLS (uni) $s = r^2, r^3, r^4, r^5$.

⁸Dolgov, Kressner, Strössner. Functional Tucker approximation using Chebyshev interpolation. SISC. 2021

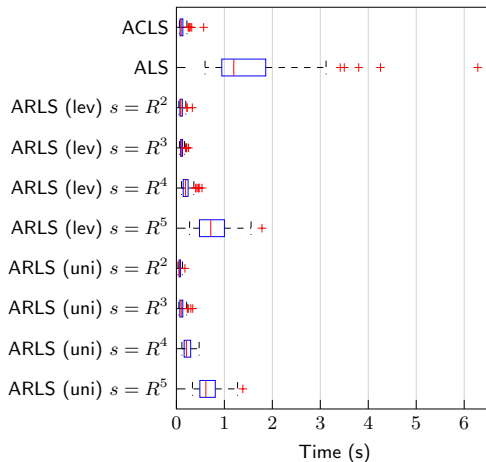


Experiment 3: discretization of a function

Fit across 100 random initializations



Runtime across 100 random initializations





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Conclusions and outlook

- Proposed CP-ACLS: a cross-based ALS variant selecting exactly r rows per LS via hierarchical `maxvol` calls on Khatri–Rao factors.
- Hierarchical `maxvol` selection costs $O(dnr^3)$ per sweep and provides a deterministic residual bound.
- Numerical experiments demonstrate competitive runtimes and accuracy at the smallest sampling budget.
- Natural extensions include oversampled cross selection and other pivoting methods.

Thank you for your attention!